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APPLICANT:

EBARA CORP;

INVENTOR:

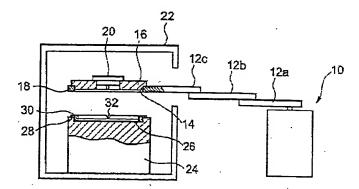
YAMAGUCHI YASUMI;

INT.CL.

H01L 21/68 B25J 9/22 B65G 49/07

TITLE

TEACHING METHOD



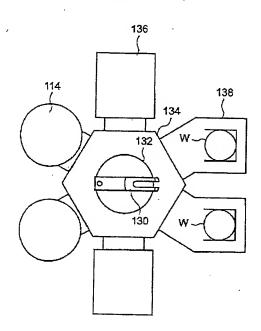
ABSTRACT:

PROBLEM TO BE SOLVED: To minimize the work and labor for teaching and reduce the transfer errors of substrates.

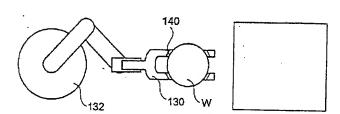
SOLUTION: In the teaching method for teaching the location of a base 24 to a controller, a teaching jig 30 having a position mark 32 made detectable by a remote sensor 20 is positioned relative to a substrate holder 12c or the base 24, and disposed on either a robot hand unit 10 or a chamber 22. The remote sensor is positioned relative to the substrate holder 12c or the base 24, and disposed on the other. The position mark is detected by the remote sensor with the substrate holder being moved by the controller, thus teaching the location of the base to the controller.

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【図11】



【図12】



フロントページの続き

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